

Jets in heavy ion collisions with fast clustering jet finders

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At RHIC, 'jet' studies look at high p_t particles and their average correlations.

Traditional (particle physics) jet studies instead seek to identify jets on an event-by-event basis, as reliable proxies for the 'original hard partons'.

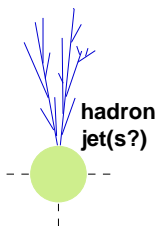
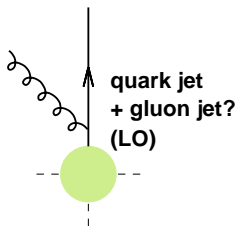
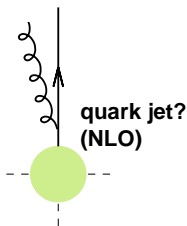
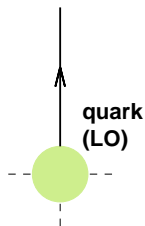
To what extent (and how) can the traditional techniques be applied in the heavy-ion environment?

Talk has two parts

- ▶ Introduction to jet definitions.
- ▶ Overview of some progress relevant to HI.

Discussion will be in context LHC (where jets will be common)

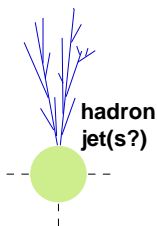
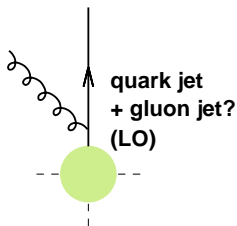
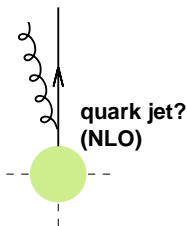
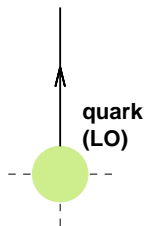
Partons (quarks, gluons) are not trouble-free concepts...



- ▶ Partons split into further partons
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General

- ▶ Infrared and collinear safety – i.e. soft emissions and collinear splittings should not change jets otherwise pert. QCD cannot be used
- ▶ Definitions should be simple and detector independent otherwise different experiments cannot compare results

Specific to HI

- ▶ It must be computationally feasible to run on the $10^4 - 10^5$ particles expected at LHC.
- ▶ Procedure to reduce large background noise should also satisfy above 'safety' properties.

Clustering jet finders

1. Calculate 'distances'
 - ▶ d_{ij} between all particles i and j
 - ▶ d_{iB} between i and beam
2. Find smallest of d_{ij} and d_{iB}
 - ▶ If d_{ij} is smallest, recombine i and j
 - ▶ if d_{iB} is smallest call i a jet
3. Goto step 1 if anything's left

Two variants (& one parameter, R)

- ▶ **k_t jet finder** [1991]

$$d_{ij} = \min(k_{ti}^2, k_{tj}^2) \Delta R_{ij}^2, \quad d_{iB} = k_{ti}^2 R^2$$

- ▶ **Cambridge/Aachen** [1998]

$$d_{ij} = \Delta R_{ij}^2, \quad d_{iB} = R^2 \quad [\Delta R_{ij}^2 = \Delta y_{ij}^2 + \Delta \phi_{ij}^2]$$

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Cone jet finders e.g.

1. Create a seed (3-vector) from the direction of each input particles (possibly implement a way to specify a smaller list of seeds to save processing time i.e. calo clusters).
2. For each seed, s , create a cone in η - ϕ space of radius R (set by the parameter radius around the seed axis such that a particle, p , with

$$(\eta_p - \eta_s)^2 + (\phi_p - \phi_s)^2 < R^2 \quad (1)$$

is defined to be inside the cone.

3. Then combine every particle in this cone into a jet using a p_{\perp} recombination scheme as described in section 2.5.2 of the KtJet paper.
4. Now create a new cone around this jet's axis and repeat step 3. If the new jet's axis is collinear with the previous axis then the jet is stable and is added to the list of meta-jets, otherwise the process is repeated until either a stable jet is found or a maximum number of iterations is reached.
5. The next stage is, to enforce infra-red safety, to repeat steps 2-4 with a new set of seeds in-between every pair of jets i, j , found above if i and j are between 1 and 2 cone radii apart i.e.

if:

$$R^2 < (\eta_i - \eta_j)^2 + (\phi_i - \phi_j)^2 < (2R)^2 \quad (2)$$

then:

$$\eta_s = \frac{\eta_i + \eta_j}{2} \quad \phi_s = \frac{\phi_i + \phi_j}{2} \quad (3)$$

6. Next any jets with p_{\perp} less than a pre-defined parameter $\epsilon_{p_{\perp}}$ (typically of order 5 GeV) are removed from the list.
7. Then for each jet in the list, if the sum of the p_{\perp} s of any particles in the jet which are shared with a higher p_{\perp} jet is greater than some fraction, ovlim , of this jet's p_{\perp} , then remove the jet from the list.
8. Next for each particle that is still in more than one jet, remove the particle from all but the closest jet to particle's direction, i.e. the jet with the smallest $\Delta(\eta)^2 + \Delta(\phi)^2$.
9. Finally step 6 is repeated.

[from W. Plano]

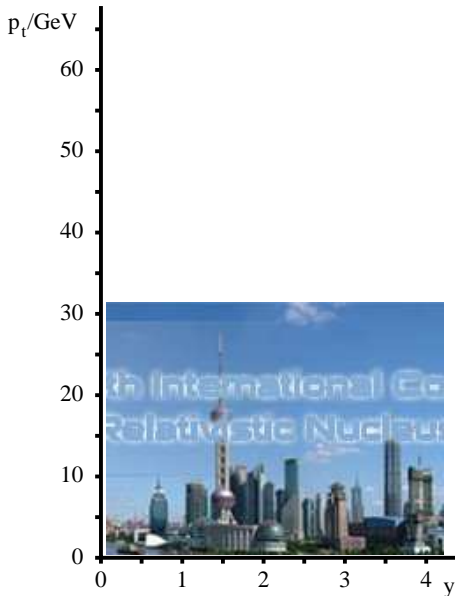
Example clustering with k_t algorithm, $R = 0.7$

ϕ assumed 0 for all towers

For Shanghai skyline, clustering is a bit arbitrary. . .

But on QCD events, d_{ij} is related to divergences for branching — clustering attempts inverse branching.



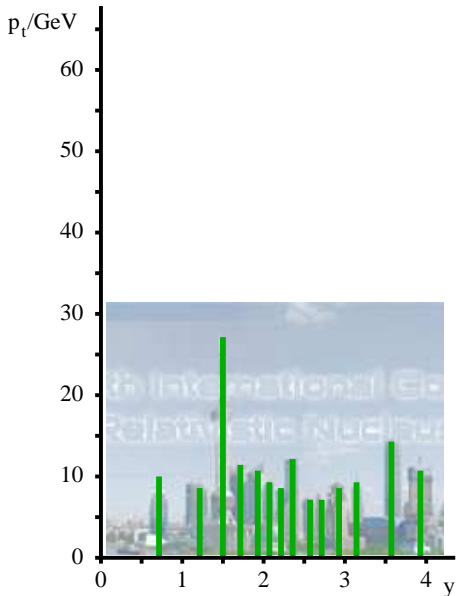


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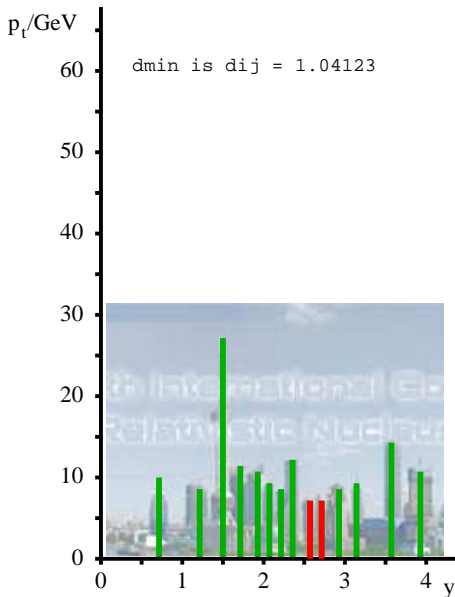


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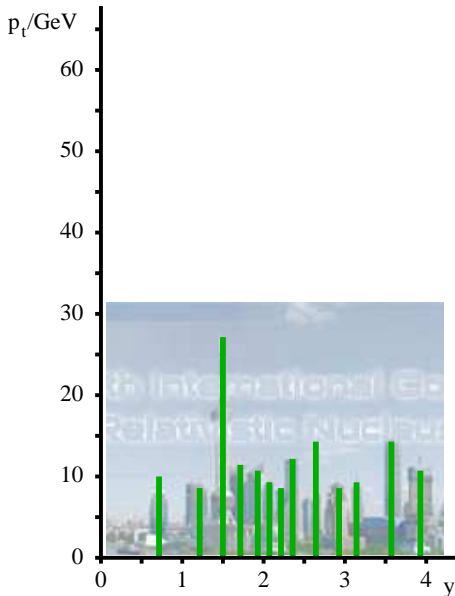


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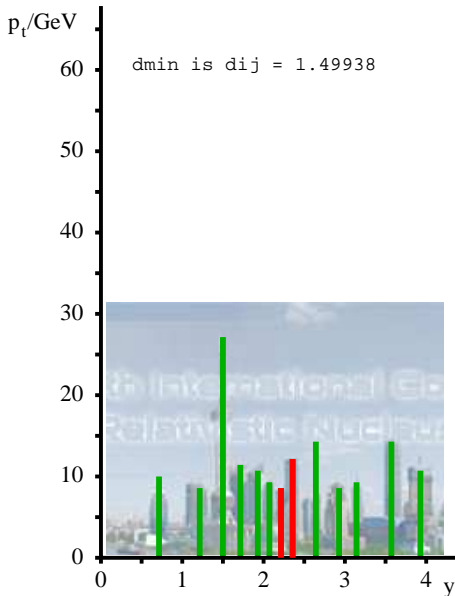


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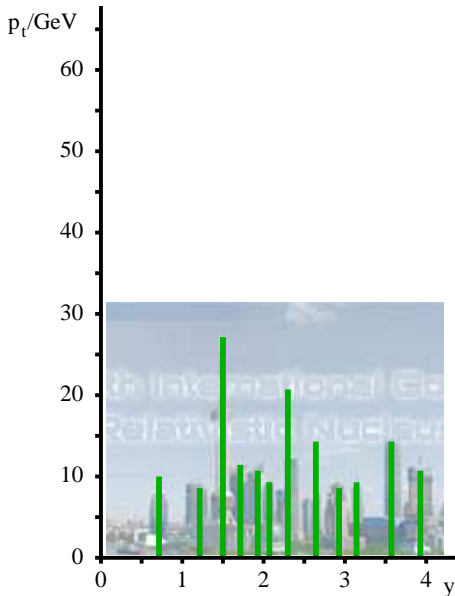


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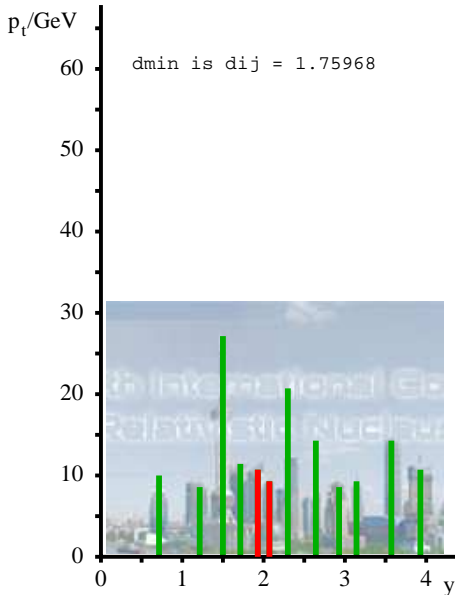


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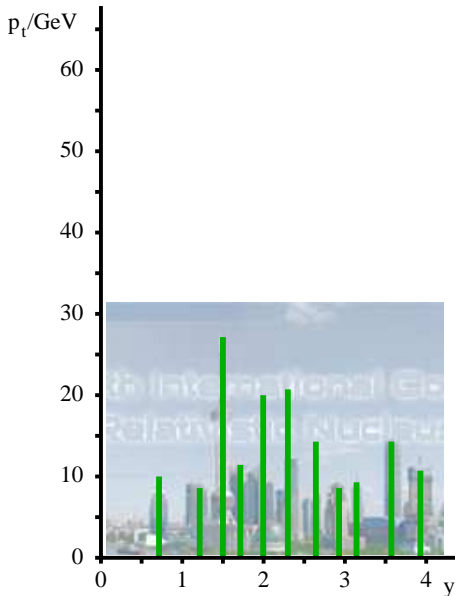


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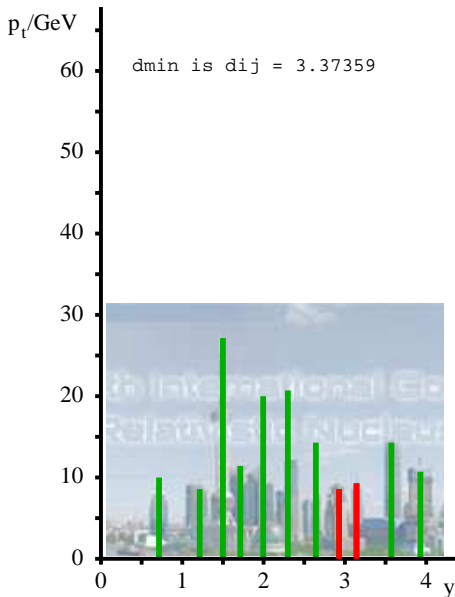


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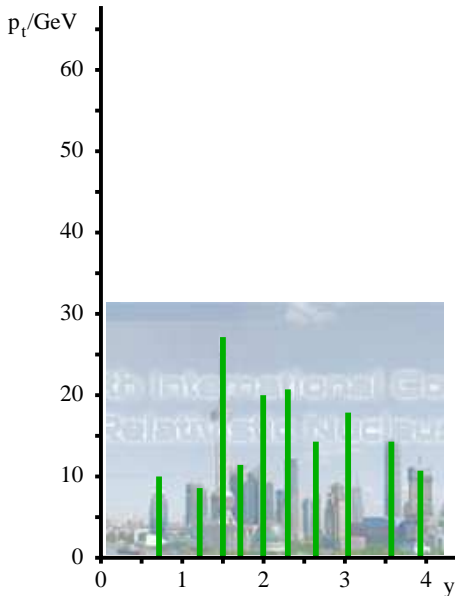


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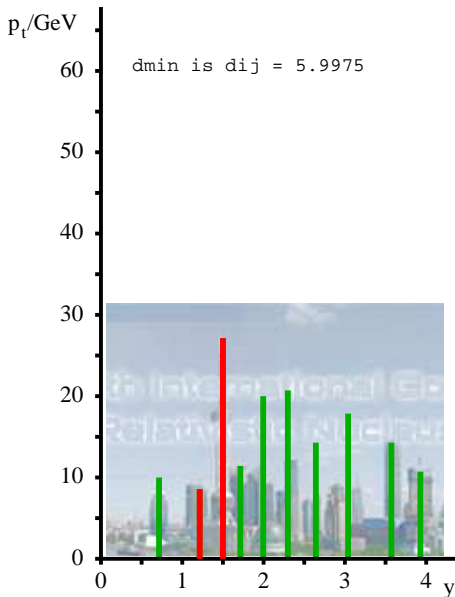


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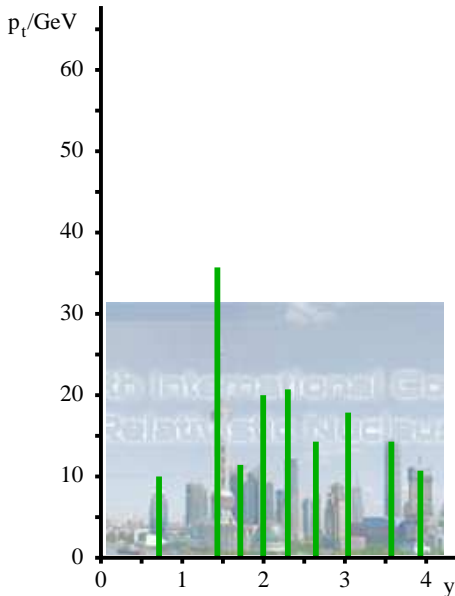


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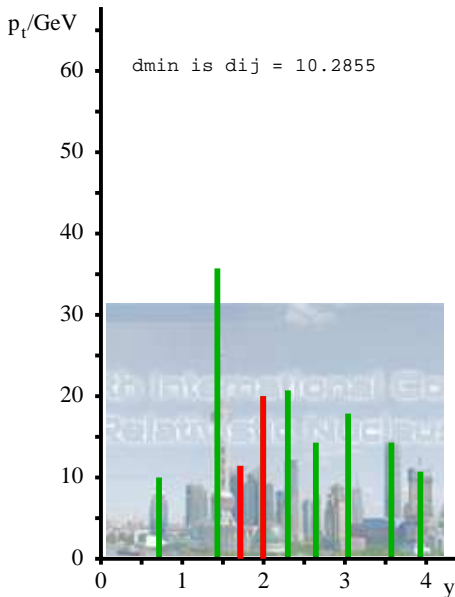


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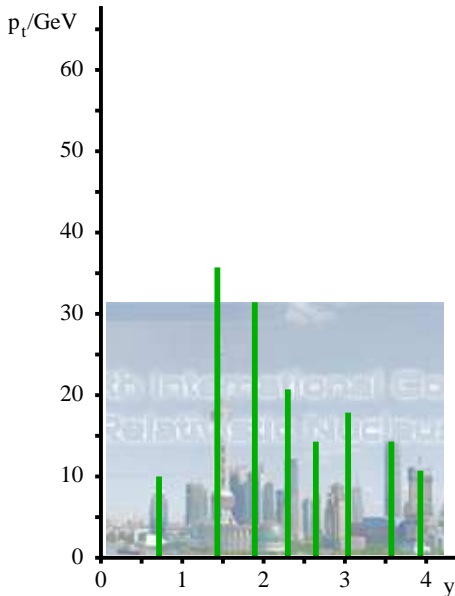


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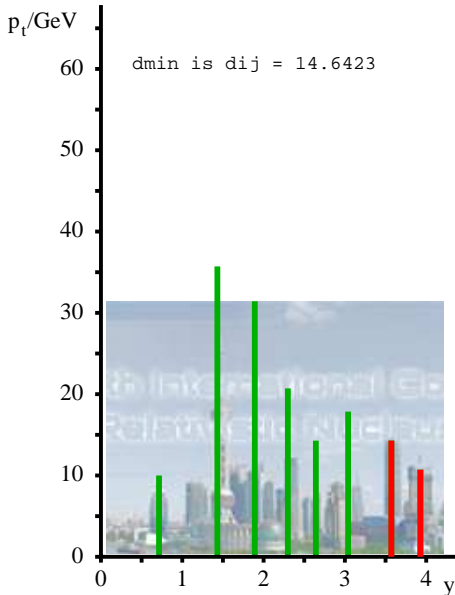


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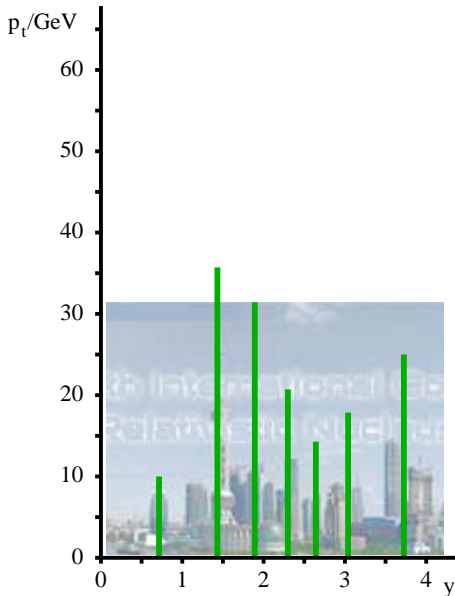


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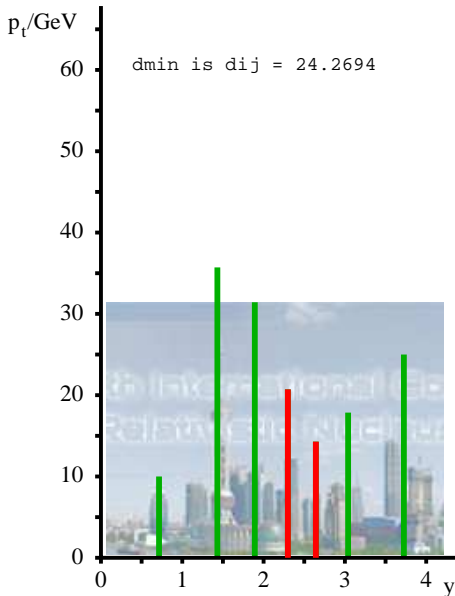


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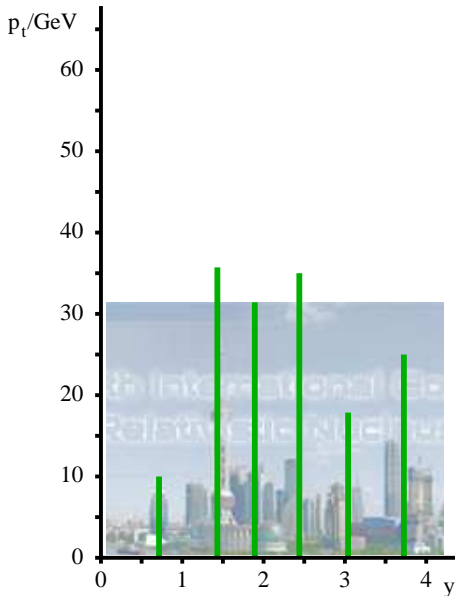


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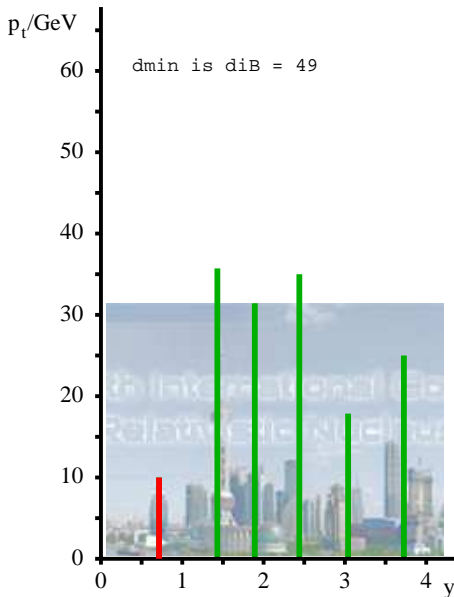


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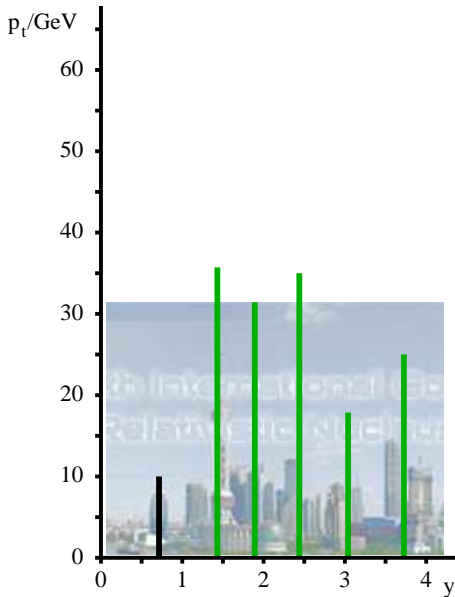


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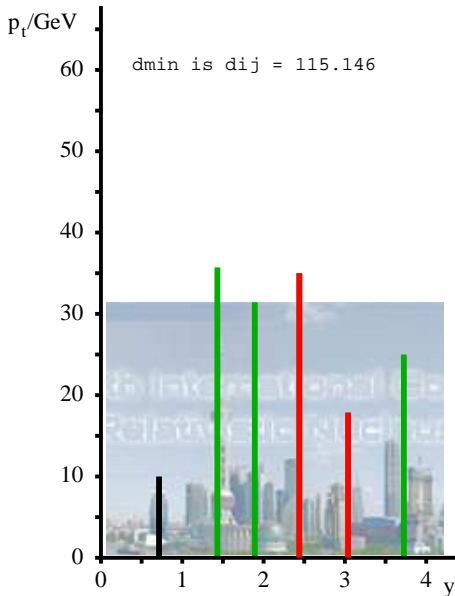


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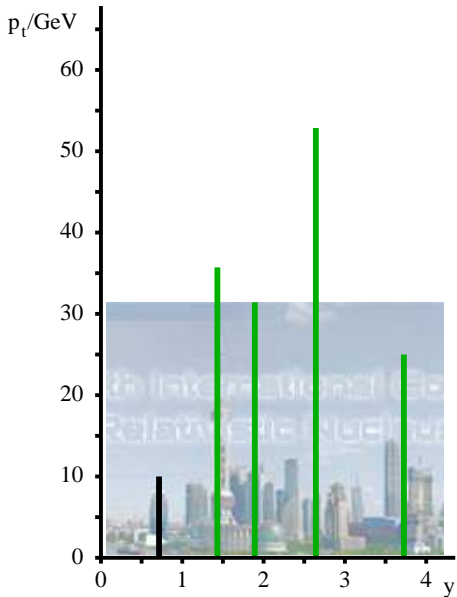


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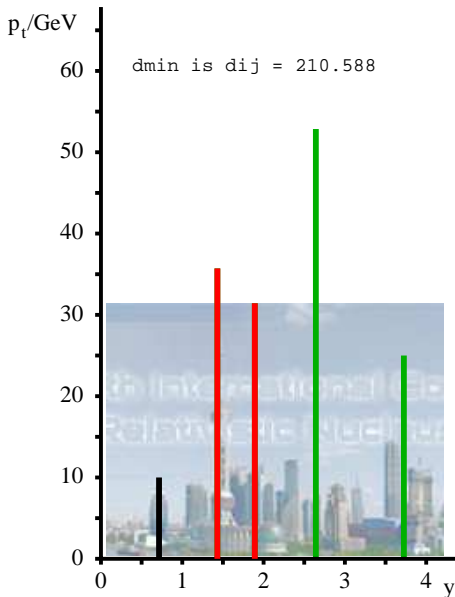


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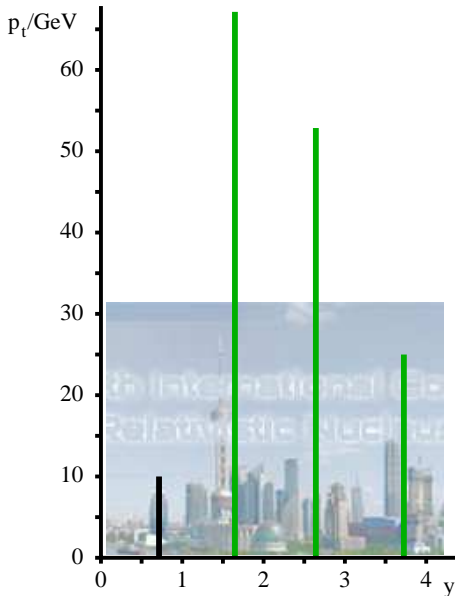


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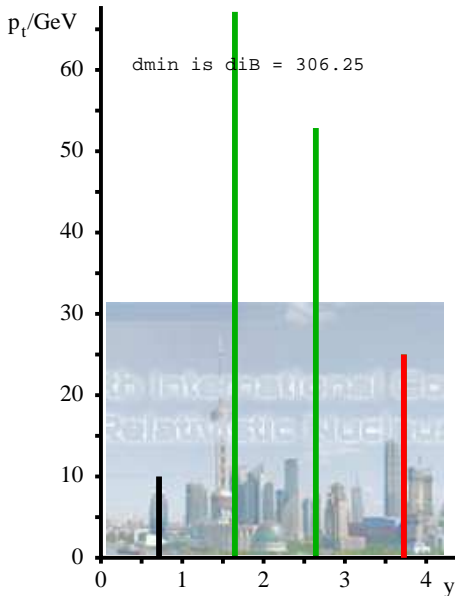


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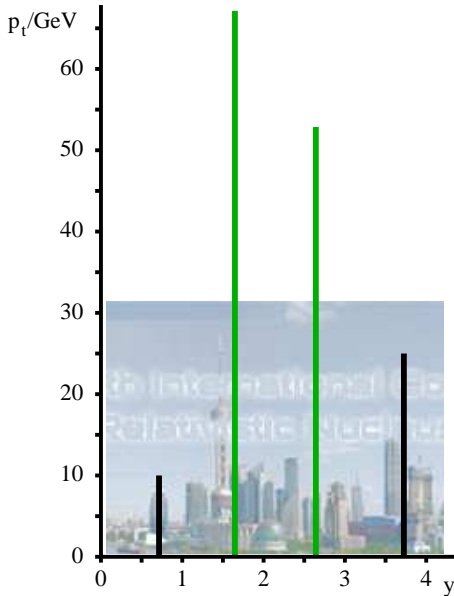


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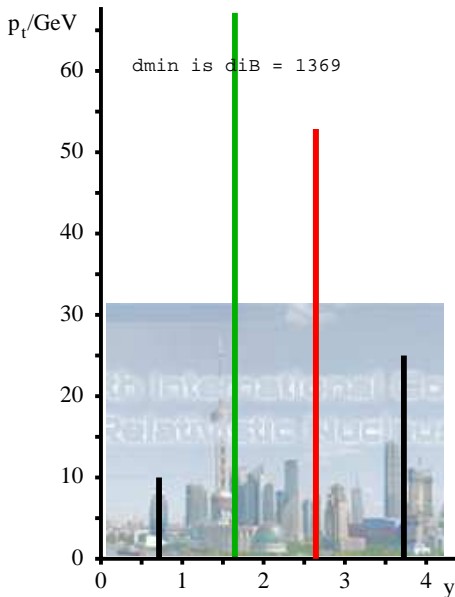


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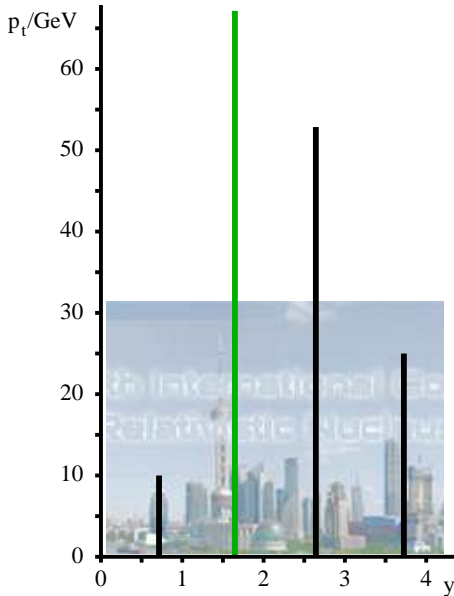


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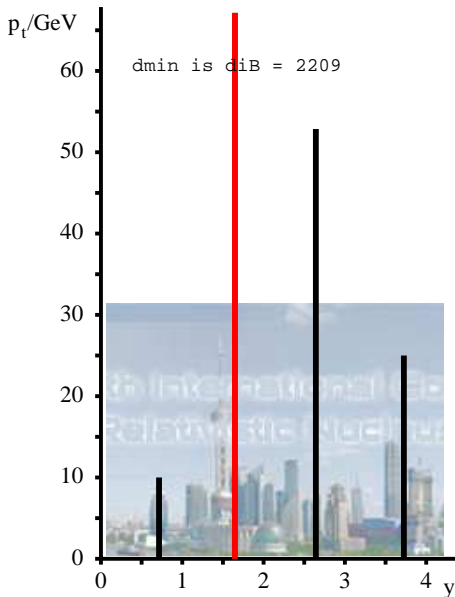


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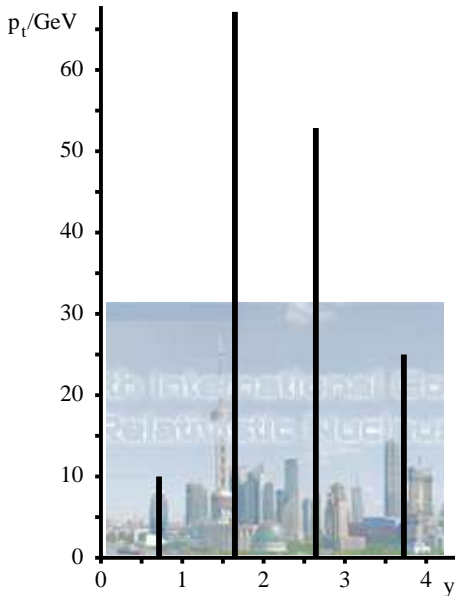


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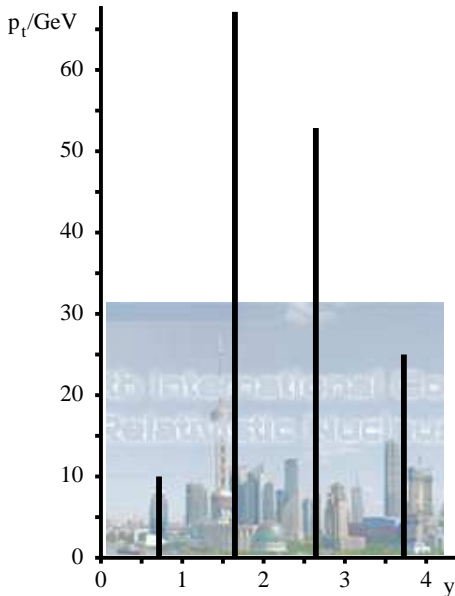


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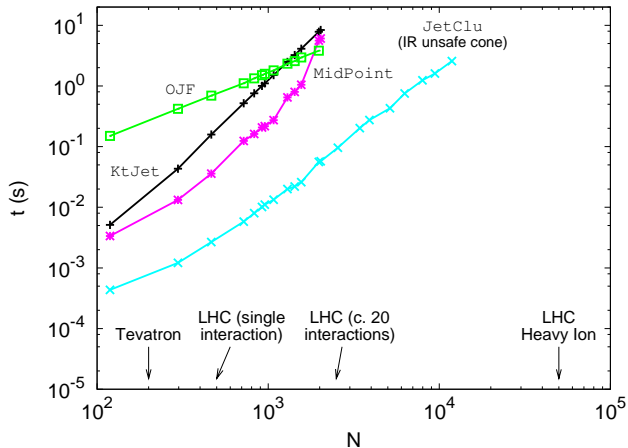
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Advantages of clustering jet finders

- ▶ They are always infrared & collinear safe.
- ▶ Simplicity → extensively studied theoretically
- ▶ They have smaller hadronization corrections than cone jet finders.
More robust wrt fine details of quenching?
- ▶ They are the standard in e^+e^- and DIS colliders
- ▶ Starting to be used at Tevatron

Issues for HI:

- ▶ Long believed to be too computationally complex for high-multiplicity environments ($N > 1000$).
- ▶ Subtraction of “background” had never been attempted

Time to cluster N particles

Standard C++ (and fortran) k_t -clustering takes time $\sim N^3$.

a Pb-Pb event takes 1 day!

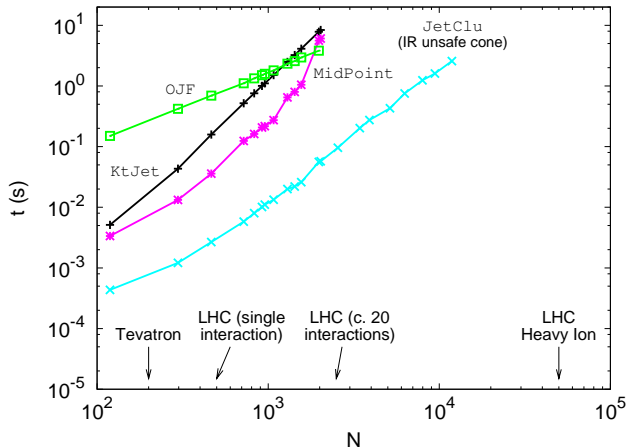
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But IR unsafe.

Discontinued at Tevatron

IR-safe cone (Mid-point) is as slow as k_t

Jet-clustering speed is an issue for high-luminosity pp ($\sim 10^8$ events) and Pb-Pb ($\sim 10^7$ events) collisions at LHC.

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How to make clustering faster?

Have $\mathcal{O}(N^2)$ distances d_{ij} to calculate. Is N^2 the best that can be done?

Problem of finding smallest d_{ij}

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can be **separated** into a momentum dependent part (k_t 's) and geometrical part (ΔR_{ij}). Cacciari & GPS '05

- ▶ mom.-dependent part depends on just one particle, $\mathcal{O}(N)$ complexity
- ▶ geometrical parts \Leftrightarrow proximity problems widely studied by **computational geometers** \rightarrow calculate only $\mathcal{O}(N \ln N)$ ΔR_{ij} 's
 - Dynamic Voronoi diagrams: Devillers '99 (and many others) / CGAL
 - Dynamic closest pair maintenance (quad-trees + shuffles): Chan '02

Put together in a C++ code — **FastJet**

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Put together in a C++ code — **FastJet**

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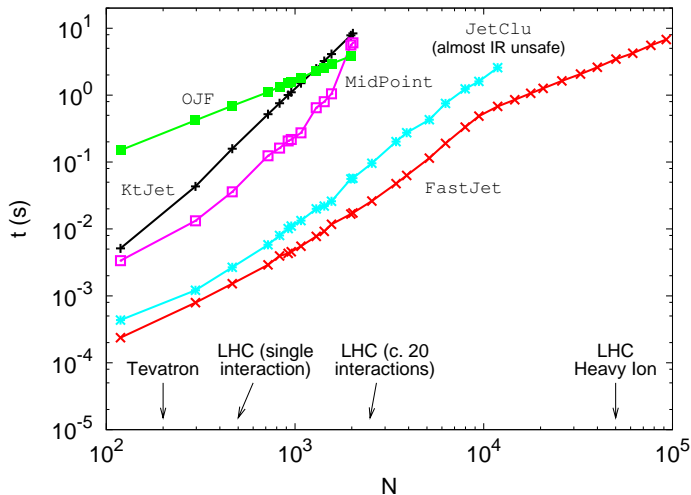
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For $N \gtrsim 10^4$, FastJet algorithm scales as $N \ln N$

For $N \lesssim 10^4$, FastJet switches to a related geometrical N^2 alg.

get code from <http://www.lpthe.jussieu.fr/~salam/fastjet>

Compared to low-lumi pp, crucial difference in Pb Pb is *huge* background.

Estimate of P_t density (ρ) at LHC:

$$\rho_{\text{background}} \equiv \frac{dP_t}{dyd\phi} \sim 250 \text{ GeV}$$

Hydjet 1.1 default, $dN_{\text{ch}}/dy = 1600$ $y = 0$ (optimistic?)

Jet contamination:

$$\Delta P_{t,\text{jet}} \simeq \rho \times \text{Area}_{\text{jet}} \quad [\text{Area} \sim \pi R^2]$$

Correct before clustering

- ▶ by removing particles with $p_t < 1 - 2 \text{ GeV}$
Collinear unsafe; who knows how it's affected by quenching...
- ▶ by subtracting energy from calorimeter cells
What to do with negative-energy cells? Experiment-dependent?

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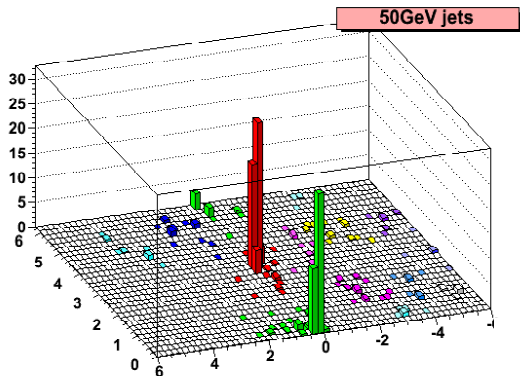
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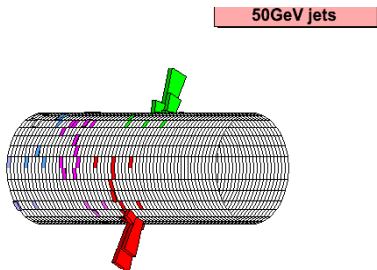


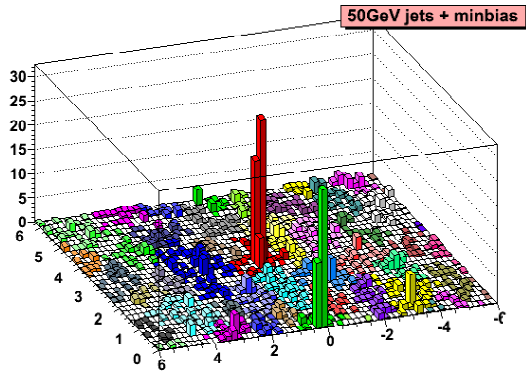
'Standard hard' event
Two well isolated jets

Jet boundaries completely unclear

~ 200 particles

Easy even with old methods





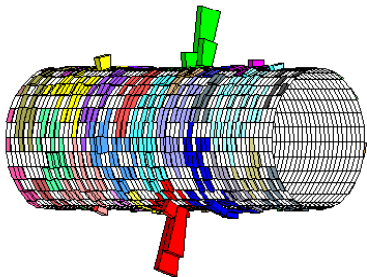
Add 10 min-bias events
(moderately high lumi
LHC pp)

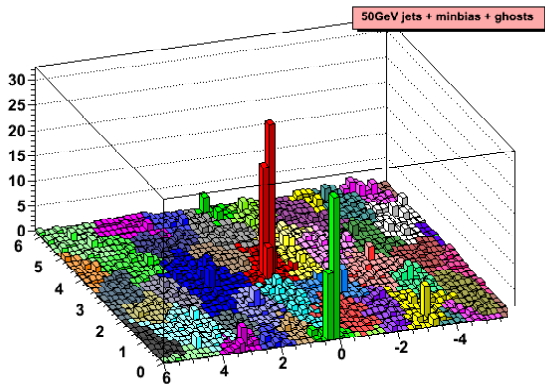
Jet boundaries still ill
defined — jets clearly
irregular

~ 2000 particles

Clustering takes $\mathcal{O}(10s)$ with old
methods.

20ms with FastJet.





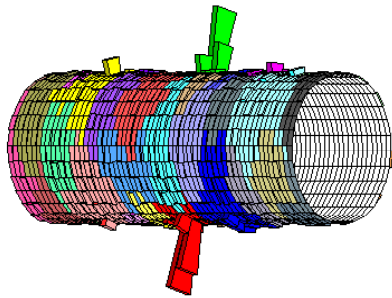
~ 10000 particles

Clustering takes ~ 20 minutes
with old methods.

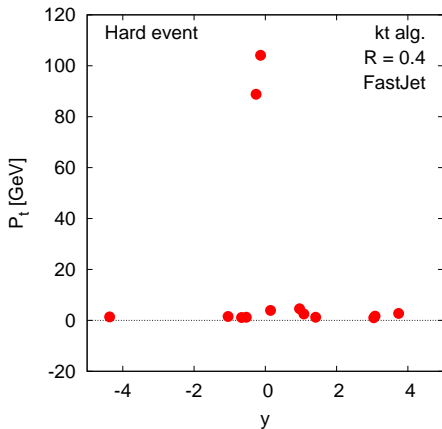
0.6s with FastJet.

Add dense coverage of infinitely soft "*ghosts*"

See how many end up in jet to measure jet area

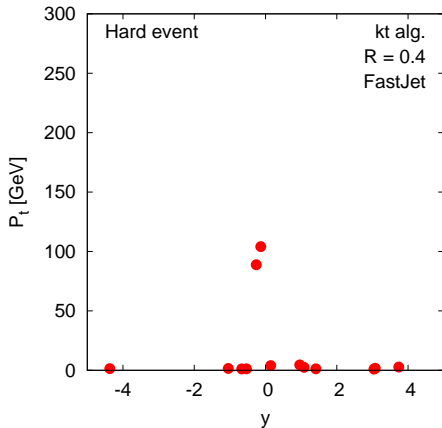
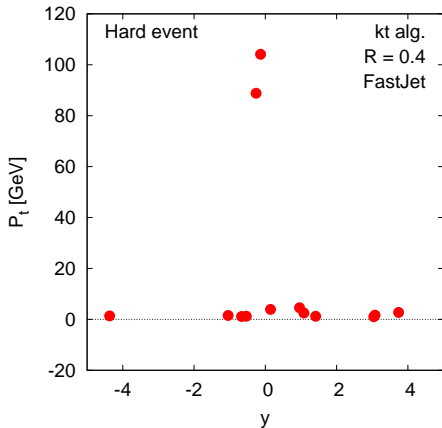


Background subtraction in HI event



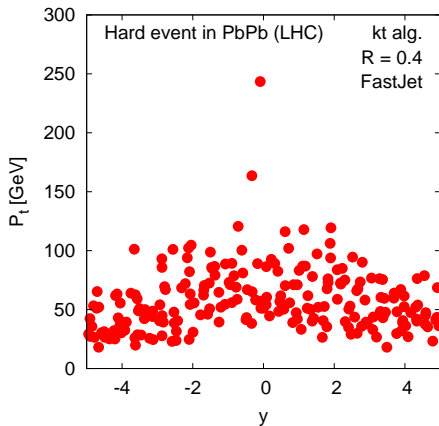
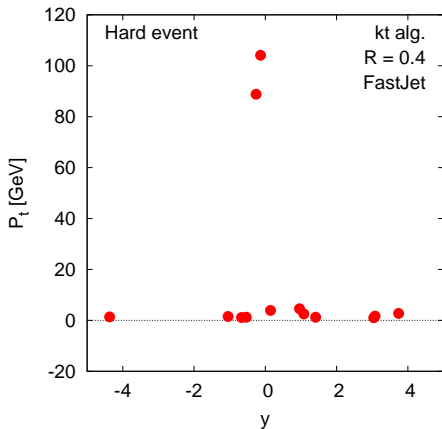
Start with a hard dijet event

Background subtraction in HI event



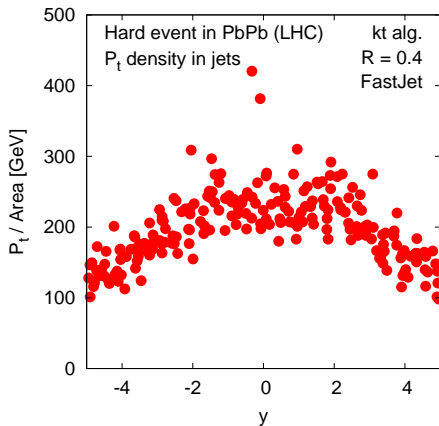
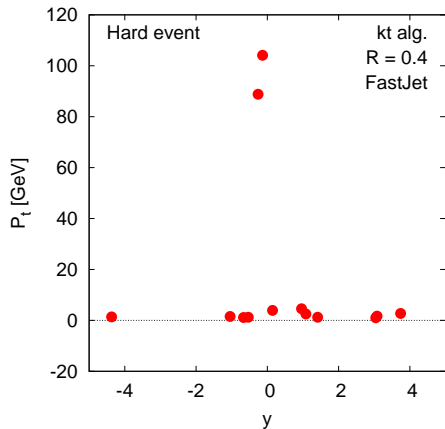
Same event on a different scale

Background subtraction in HI event



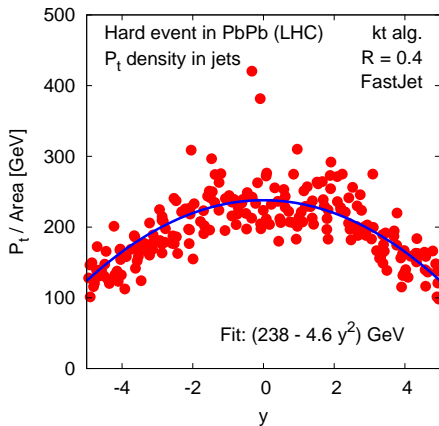
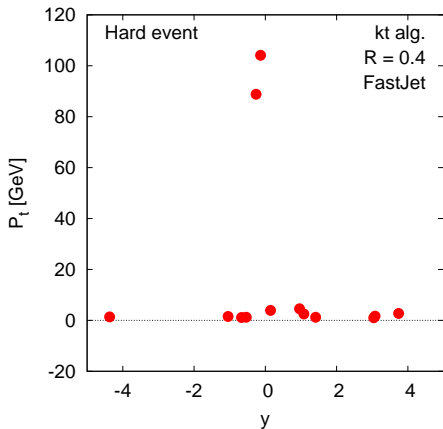
Embed it into a central Hydjet Pb Pb event

Background subtraction in HI event



Look at P_t / Area for each jet

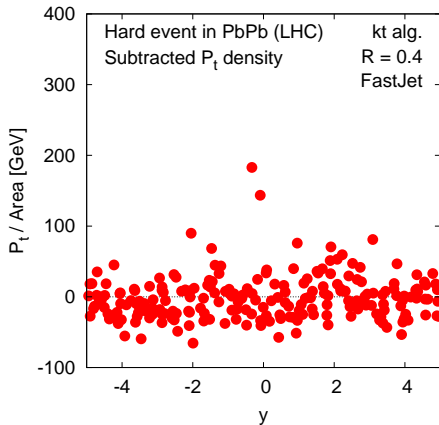
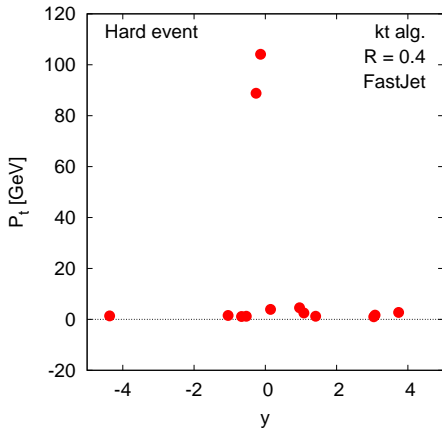
Background subtraction in HI event



Fit the background $\rho(y)$

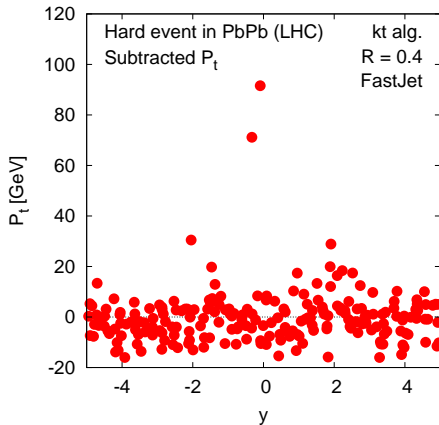
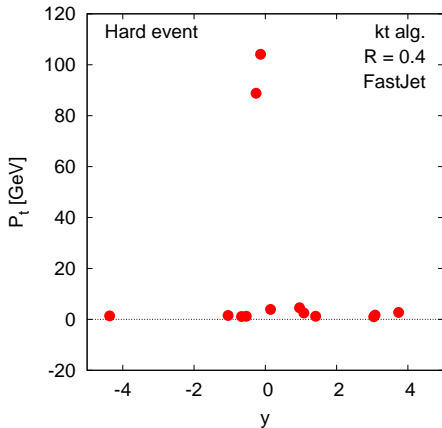
[NB: more general functional form needs investigating]

Background subtraction in HI event



Subtract $\rho(y)$ from P_t / Area for each jet

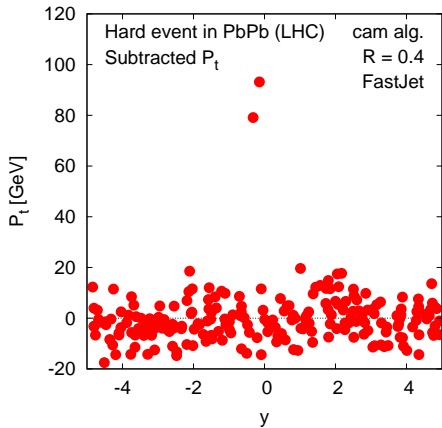
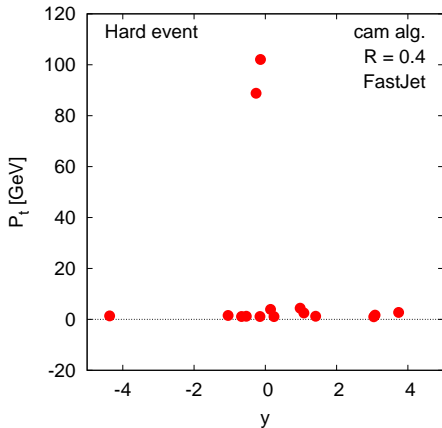
Background subtraction in HI event



Look at resulting corrected $P_t = P_{t,orig} - \rho(y) \times Area$

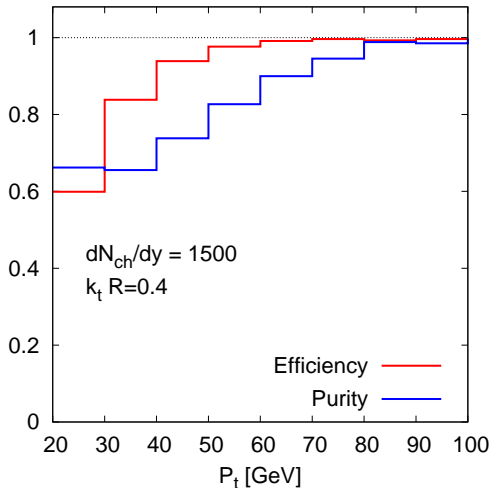
Hard jets with roughly correct P_t and y emerge clearly!

Background subtraction in HI event



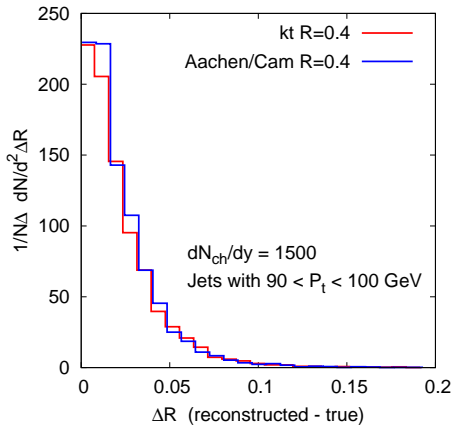
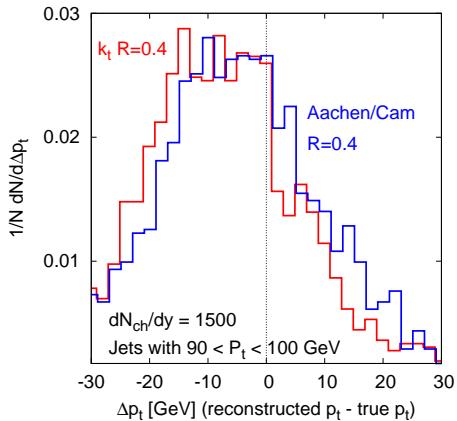
Try with Cambridge/Aachen instead of k_t to check robustness!

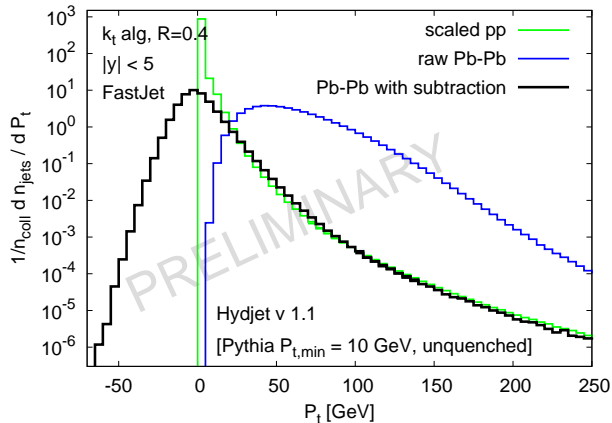
Reconstruction efficiency & purity

Procedure:

A reconstructed jet within $\Delta R < 0.2$ of the original jet is considered to correspond to the original one.

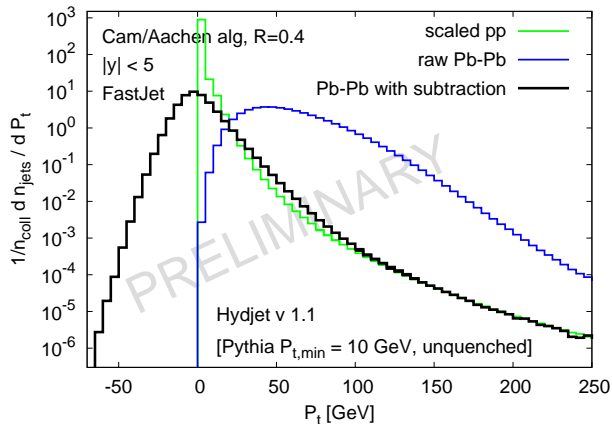
NB: detector effects are likely to adversely affect these figures.





Inclusive jet spectrum is most basic measurement in pp .

Interesting to check also in PbPb?



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Issues that “used to be”, are no longer

- ▶ Speed: was N^3 , now $N \ln N$; these are the fastest particle-level jet finders on the market!
- ▶ Ill-defined jet boundaries & area: add soft “ghosts” to track jet layout.
- ▶ **FastJet** code provides access to these tools.

Question of background subtraction is still open

- ▶ There are methods for doing it before clustering [ALICE, CMS, ATLAS], and after clustering [this talk].
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In a standardized, collinear-safe, detector-independent formulation?
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EXTRA MATERIAL

Why was k_t an N^3 algorithm?

1. Given the initial set of particles, construct a table of all the d_{ij} , d_{iB} .
[$\mathcal{O}(N^2)$ operations, done once]
2. Scan the table to find the minimal value d_{\min} of the d_{ij} , d_{iB} .
[$\mathcal{O}(N^2)$ operations, done N times]
3. Merge or remove the particles corresponding to d_{\min} as appropriate.
[$\mathcal{O}(1)$ operations, done N times]
4. Update the table of d_{ij} , d_{iB} to take into account the merging or removal, and if any particles are left go to step 2.
[$\mathcal{O}(N)$ operations, done N times]

This is the “brute-force” or “naive” method

There are $N(N - 1)/2$ distances d_{ij} — surely we have to calculate them all in order to find smallest?

k_t distance measure is partly *geometrical*:

- ▶ Consider smallest $d_{ij} = \min(k_{ti}^2, k_{tj}^2) R_{ij}^2$
- ▶ Suppose $k_{ti} < k_{tj}$
- ▶ Then: $R_{ij} \leq R_{i\ell}$ for any $\ell \neq j$. [If $\exists \ell$ s.t. $R_{i\ell} < R_{ij}$ then $d_{i\ell} < d_{ij}$]

In words: if i, j form smallest d_{ij} then j is geometrical nearest neighbour (GNN) of i .

k_t distance need only be calculated between GNNs

Each point has 1 GNN \rightarrow need only calculate N d_{ij} 's

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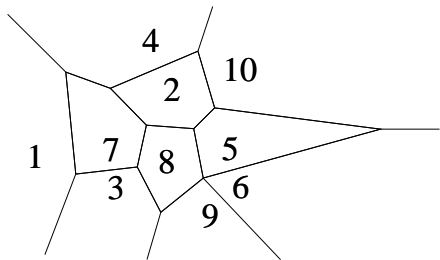
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Finding Geom Nearest Neighbours



Given a set of vertices on plane (1...10) a *Voronoi diagram* partitions plane into cells containing all points closest to each vertex

Dirichlet '1850, Voronoi '1908

A vertex's nearest other vertex is always in an adjacent cell.

E.g. GNN of point 7 will be found among 1,4,2,8,3 (it turns out to be 3)

Construction of Voronoi diagram for N points: $N \ln N$ time Fortune '88

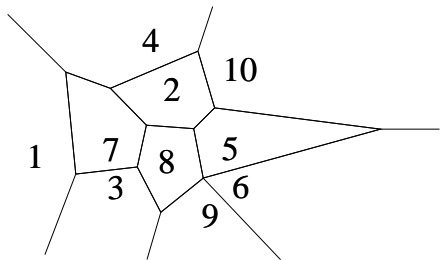
Update of 1 point in Voronoi diagram: $\ln N$ time

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Convenient C++ package available: CGAL

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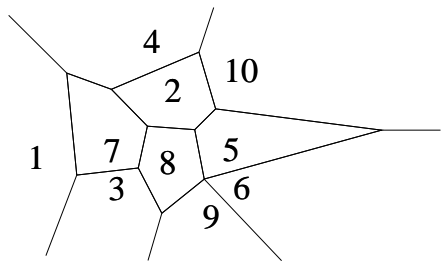
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The FastJet algorithm:

Construct the Voronoi diagram of the N particles with CGAL $\mathcal{O}(N \ln N)$

Find the GNN of each of the N particles, calculate d_{ij} store result in a *priority queue* (C++ map) $\mathcal{O}(N \ln N)$

Repeat following steps N times:

- ▶ Find smallest d_{ij} , merge/eliminate i, j $N \times \mathcal{O}(1)$
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Overall an $\mathcal{O}(N \ln N)$ algorithm

Cacciari & GPS, hep-ph/0512210

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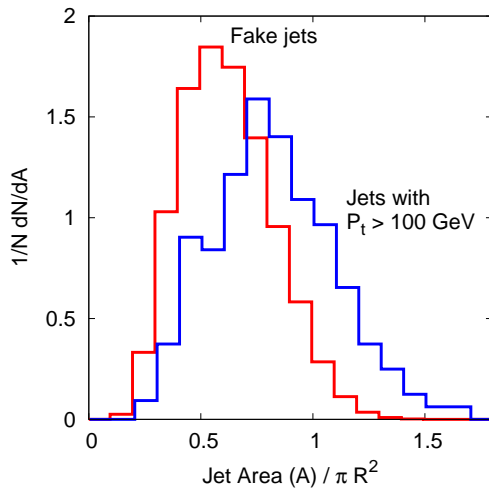
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Results identical to standard N^3 implementations



Each jet has a different area

True jets can have internal structure (parton branching) — jet area expands to accommodate this.

Fake jets little internal structure → jet areas smaller.

NB: jet areas often $< \pi R^2$